# Using ROS CLI File Commands

These commands all allow the user to do file operations on files in ROS packages.

## rosed

rosed allows for editing a file in a ROS package from any location.

Usage:

```
rosed <PACKAGE> <FILE>
```

## roscat

roscat allows for files in a ROS package to be echoed to the screen from any location.

Usage:

```
roscat <PACKAGE> <FILE>
```

## roscd

roscd allows for the user to cd directly to any folder in a ROS package.

Usage:

```
roscd <PACKAGE>/<PATH>
```

## roscp

roscp allows for the user to copy a file from a ROS package to any directory.

Usage:

```
roscp <PACKAGE> <FILE> <TARGET>
```

## rosls

rosls allows a user to see files in a package.

Usage:

```
rosls <PACKAGE>/<PATH>
```

From:

<https://robosub.eecs.wsu.edu/wiki/> - **Palouse RoboSub Technical Documentation**

Permanent link:

**https://robosub.eecs.wsu.edu/wiki/cs/ros/rosfiles/start**



Last update: **2017/01/14 20:44**