Simulator

The current simulator uses Gazebo and is integrated with ROS. For information about running the simulator look here.

From:

https://robosub.eecs.wsu.edu/wiki/ - **Palouse RoboSub Technical Documentation**

Permanent link:

https://robosub.eecs.wsu.edu/wiki/cs/simulator/start

Last update: **2022/04/15 02:32**