Simulator

Gazebo Install

The current simulator uses Gazebo and is integrated with ROS. For information about running the simulator look here.

From:
https://robosub.eecs.wsu.edu/wiki/ - **Palouse RoboSub Technical Documentation**

Permanent link:
https://robosub.eecs.wsu.edu/wiki/cs/simulator/start?rev=1650015130

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