

Image Tagging

Sloth

Setup

In order to tag images, we use a piece of software called Sloth. To install it from the robosub debian repository, run the following command:

```
sudo aptitude install sloth
```

Using Sloth

To use sloth and start tagging images, you can run the following command.

```
sloth -c /path/to/vision_dev/sloth/robosub_config.py  
/path/to/annotation/file
```

`*-c*` Is a flag to give the path to a configuration file. This file is provided in the vision_dev/sloth directory. The path you provide should point to this file.

The last argument is a path to an annotation file. This is most likely named something like ``labels.json``. You will need to provide this path in order to tag images.

Should you find this tedious, there is a script in the sloth directory of the vision_dev repository which performs some of this for you. It can be used as follows:

```
./robosub_sloth.sh /path/to/annotation/file
```

This removes the need to add the `-c` flag repeatedly. This script can also be symlinked to without issues.

Sloth Keybindings

The full list of keybindings used in sloth can be found in the [robosub_config.py](#) file near the bottom. A shorthand list is provided below

Default keybindings

- **Space** Mark image as labeled/confirmed and go to next

- **Backspace** Next image/frame
- **PgDown** Previous image/frame
- **PgUp** Previous image/frame
- **Tab** Select next annotation
- **Shift+Tab** Select previous annotation
- **Ctrl+f** Fit current image/frame into window
- **Del** Delete selected annotations
- **Esc** Exit insert mode
- **Shift+l** Mark current image as labeled
- **Shift+c** Mark all annotations in image as confirmed

Robosub Specific

- **F5** Toggle the visibility of label names on annotation boxes
- **Ctrl+Shift+Del** Delete all annotations from the current image and mark it as unlabeled
- **c** Copy all annotations from the previous image to this one
- **n** Mark image as labeled/confirmed and go to next then copy all annotations from the previous image.
(Equivalent to **Space** then **c**)

Annotations

- **r** Red Buoy
- **y** Yellow Buoy
- **g** Green Buoy
- **s** Start Gate Post
- **p** Path Marker
- **m** Marker Drop Platform
- **,** Object Pickup Platform
- **.** Object Drop-off Platform
- **h** Hexagon
- **t** Torpedo Target
- **z** Navigation Channel Post
- **x** Navigation Channel Bar

Sloth Mouse Controls

While creating annotations, the following are useful mouse controls.

- **Right Click and Drag**

Resize an annotation. Resizing is based upon the quadrant of the annotation clicked on.

- **Ctrl+Left Click**

Select multiple annotations at once.

Getting Data to Label

We use the `download_data.sh` and `download_data_current.sh` scripts from the [vision_dev](#) repository to get data from the server. Make sure that you always do a git pull before getting new data because the scripts change frequently.

First claim one or more batches to label from the current spreadsheet of data. The current spreadsheet is located [here](#). Note which numbers you want.

Once you have claimed some batches run the following command in `vision_dev` to download and extract the data:

```
./download_data.sh bag_prefix_0 ## ## ##
```

For example if you want batch numbers 00 04 and 12 of the `path_marker` batch you would run:

```
./download_data.sh path_marker_0 00 04 12
```

Before downloading the data it will ask you for a username and password, please ask in either the it or general channels on [slack](#)

Uploading Data

Here is the [upload link](#) for .json files. Just drag and drop it.

From:

<https://robosub.eecs.wsu.edu/wiki/> - **Palouse RoboSub Technical Documentation**

Permanent link:

https://robosub.eecs.wsu.edu/wiki/cs/vision/image_tagging/start?rev=1519832752

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