

Hydrophones

Our hydrophones are a powerful tool for figuring out where we are in the water. Using 4 hydrophones, we can calculate our bearing to the pinger. For details, see [Pinger Bearing](#).

Testing Procedure

Materials:

- 1 tub of water
- 1 pinger
- Hydrophone Test Rig

Test Rig:

- Pinger at one end of tub
- Hydrophones at other end of tub
- If lots of noise in readings observed, can place towels around tub

Procedure:

1. ssh into the sub
2. `roslaunch robosub cobalt.launch`
3. `roslaunch robosub pinger_bearing`
4. `rostopic echo /hydrophones/bearing`
5. Manipulate hydrophones & Observe bearing readings

From:

<https://robosub.eecs.wsu.edu/wiki/> - **Palouse RoboSub Technical Documentation**

Permanent link:

<https://robosub.eecs.wsu.edu/wiki/cs/hydrophones/start?rev=1550807436>



Last update: **2019/02/21 19:50**