Installation

For Ubuntu 14.04, you can just follow the normal ⠿ROS installation instructions.

For Linux Mint 17.x, the instructions are mostly the same, here are the steps:

```
sudo sh -c '. /etc/lsb-release && echo "deb
http://mirror.umd.edu/packages.ros.org/ros/ubuntu trusty main" >
/etc/apt/sources.list.d/ros-latest.list'
wget https://raw.githubusercontent.com/ros/rosdistro/master/ros.key -O - |
sudo apt-key add -
sudo aptitude install ros-indigo-ros-base
```

http://insane-on-linux.blogspot.com/2014/10/installing-ros-indigo-on-mint-17.html

Errors and Known Solutions

If you get the following error:

```
ImportError: "from catkin_pkg.package import parse_package" failed: No
module named catkin_pkg.package
```

Make sure that you have installed "catkin_pkg", it is up to date and on the PYTHONPATH:

```
$ pip install catkin_pkg
```

Error:

```
ImportError: No module named rospkg
```

Fix:

```
$ apt-get install python-rospkg
$ export PYTHONPATH=$PYTHONPATH:/usr/lib/python2.7/dist-packages
```

This is kinda a hack, haven't bothered to figure out how to properly install python-rospkg to the proper python location for indigo

If you get this error:

```
ERROR: the following packages/stacks could not have their rosdep keys
resolved to system dependencies: ardrone_autonomy: Unsupported OS [mint]
```

when running any rosdep command, add the flag —os=ubuntu:trusty to the command.

From:
https://robosub.eecs.wsu.edu/wiki/ - **Palouse RoboSub Technical Documentation**

Permanent link:
https://robosub.eecs.wsu.edu/wiki/cs/ros/installation/start?rev=1472792480

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