

Using ROS Bag

ROS bag is a nice tool for recording any data that you need to be able to play back at a later time.

The normal usage is:

```
rosv bag record <TOPIC1> ... <TOPIC(N)>
```

If you want to

From:

<https://robosub.eecs.wsu.edu/wiki/> - **Palouse RoboSub Technical Documentation**

Permanent link:

<https://robosub.eecs.wsu.edu/wiki/cs/ros/rosbag/start?rev=1475973178>



Last update: **2016/10/08 17:32**