Using ROS Console

ROS Console is useful for changing the logging level for one or more nodes.

**Viewing the Current Logging Level**

To see the current logging level for a node:

```bash
global::rosconsole get <NODE> <LOGGER>
```

The LOGGER parameter allows the user to choose specific logger messages to increase the level of. normally it is sufficient to use `ros.robosub` as the logger unless you think there is a problem with ROS itself. In that case use `ros`.

**Setting the Logger Level**

```bash
global::rosconsole set <NODE> <LOGGER>
```

**Get all of the Loggers for a Node**

```bash
global::rosconsole list <NODE>
```