

# Using ROS Console

ROS Console is useful for changing the logging level for one or more nodes.

## Viewing the Current Logging Level

To see the current logging level for a node:

```
rosconsole get <NODE> <LOGGER>
```

The `LOGGER` parameter allows the user to choose specific logger messages to increase the level of. normally it is sufficient to use `ros . robosub` as the logger unless you think there is a problem with ROS itself. In that case use `ros`.

## Setting the Logger Level

```
rosconsole set <NODE> <LOGGER>
```

## Get all of the Loggers for a Node

```
rosconsole list <NODE>
```

From:

<https://robosub.eecs.wsu.edu/wiki/> - **Palouse RoboSub Technical Documentation**

Permanent link:

<https://robosub.eecs.wsu.edu/wiki/cs/ros/rosconsole/start>



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