Using ROS Node

This command allows the user to gather information about any running node.

Getting Node Info

```bash
rosnode info <NODE>
```

Pinging a Node

```bash
rosnode ping <NODE>
```

Listing Running Nodes

```bash
rosnode list
```

Get a List of All Machines on the Network

```bash
rosnode machine
```

Get a List of Nodes Running on a Machine

```bash
rosnode machine <MACHINE_NAME>
```

Kill a Running Node

```bash
rosnode kill <NODE>
```

Clean the Server of Unresponsive Nodes

```bash
rosnode cleanup
```