Using ROS Node

This command allows the user to gather information about any running node.

**Getting Node Info**

```
rosnode info <NODE>
```

**Pinging a Node**

```
rosnode ping <NODE>
```

**Listing Running Nodes**

```
rosnode list
```

**Get a List of All Machines on the Network**

```
rosnode machine
```

**Get a List of Nodes Running on a Machine**

```
rosnode machine <MACHINE_NAME>
```

**Kill a Running Node**

```
rosnode kill <NODE>
```

**Clean the Server of Unresponsive Nodes**

```
rosnode cleanup
```

From: https://robosub.eecs.wsu.edu/wiki/ - Palouse RoboSub Technical Documentation

Permanent link: https://robosub.eecs.wsu.edu/wiki/cs/ros/rosnode/start

Last update: 2017/01/18 17:32