

Using ROS Param

This command allows for retrieval and manipulation of the parameter server.

Get Params

```
rosparam get <PARAM>
```

Set Params

```
rosparam set <PARAM> <VALUE>
```

Load Params

```
rosparam load <FILE>
```

Dump Params

```
rosparam dump <FILE>
```

List Params

```
rosparam list
```

From:

<http://134.121.64.127/wiki/> - **Palouse RoboSub Technical Documentation**

Permanent link:

<http://134.121.64.127/wiki/cs/ros/rosparam/start>

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