

# Using ROS Param

This command allows for retrieval and manipulation of the parameter server.

From:

<https://robosub.eecs.wsu.edu/wiki/> - **Palouse RoboSub Technical Documentation**

Permanent link:

<https://robosub.eecs.wsu.edu/wiki/cs/ros/rosparam/start?rev=1484790554>

Last update: **2017/01/18 17:49**

