

Using ROS Topic

Bandwidth Usage

```
rostopic bw <TOPIC>
```

Topic Delay

```
rostopic delay <TOPIC>
```

Topic Echoing

```
rostopic echo <TOPIC>
```

Topic Frequency

```
rostopic hz <TOPIC>
```

Topic Info

```
rostopic info <TOPIC>
```

List Topics

```
rostopic list
```

Publish to a topic

```
rostopic pub [-r RATE] <TOPIC> <TYPE> <DATA>
```

From:

<http://robosub.eecs.wsu.edu/wiki/> - **Palouse RoboSub Technical Documentation**

Permanent link:

<http://robosub.eecs.wsu.edu/wiki/cs/ros/rostopic/start>

Last update: **2017/01/20 15:26**

