Using ROS Topic

**Bandwidth Usage**

rostopic bw <TOPIC>

**Topic Delay**

rostopic delay <TOPIC>

**Topic Echoing**

rostopic echo <TOPIC>

**Topic Frequency**

rostopic hz <TOPIC>

**Topic Info**

rostopic info <TOPIC>

**List Topics**

rostopic list

**Publish to a topic**

rostopic pub [-r RATE] <TOPIC> <TYPE> <DATA>

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