

# ROS

We use ROS as our IPC framework.

- [Installation](#)
- [common errors and fixes](#)

From:

<https://robosub.eecs.wsu.edu/wiki/> - **Palouse RoboSub Technical Documentation**

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<https://robosub.eecs.wsu.edu/wiki/cs/ros/start?rev=1473456255>



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