

# ROS

We use ROS as our communication framework to allow different processes to talk with each other.

## Learning ROS

The [official ROS tutorials](#) are very comprehensive, however I found the way they present ROS to a beginner to be a very steep learning curve. Here is our own set of tutorials, which are a work in progress.

## Issues

Check out this page for common errors and fixes: [common errors and fixes](#)

From:

<https://robosub.eecs.wsu.edu/wiki/> - **Palouse RoboSub Technical Documentation**

Permanent link:

<https://robosub.eecs.wsu.edu/wiki/cs/ros/start?rev=1473467160>



Last update: **2016/09/09 17:26**