Roscore Daemon

Some may find it convenient to have roscore automatically launched as a system service on startup. To do this:

```
rosrun robot_upstart install --job roscore robosub/launch/roscore.launch
```

Once installed, you can use the normal service tools to manage the service:

```
sudo service roscore status
sudo service roscore start
sudo service roscore restart
sudo service roscore stop
```

To uninstall the service:

```
rosrun robot_upstart uninstall roscore
```

References: [http://docs.ros.org/jade/api/robot_upstart/html/](http://docs.ros.org/jade/api/robot_upstart/html/)

From: [https://robosub.eecs.wsu.edu/wiki/ - Palouse RoboSub Technical Documentation](https://robosub.eecs.wsu.edu/wiki/)

Permanent link: [https://robosub.eecs.wsu.edu/wiki/cs/roscore_daemon/start](https://robosub.eecs.wsu.edu/wiki/cs/roscore_daemon/start)

Last update: 2016/10/09 13:13