

Roscore Daemon

Some may find it convenient to have roscore automatically launched as a system service on startup. To do this:

```
rosrun robot_upstart install --job roscore robosub/launch/roscore.launch
```

Once installed, you can use the normal service tools to manage the service:

```
sudo service roscore status  
sudo service roscore start  
sudo service roscore restart  
sudo service roscore stop
```

To uninstall the service:

```
rosrun robot_upstart uninstall roscore
```

References: http://docs.ros.org/jade/api/robot_upstart/html/

From:

<https://robosub.eecs.wsu.edu/wiki/> - **Palouse RoboSub Technical Documentation**

Permanent link:

https://robosub.eecs.wsu.edu/wiki/cs/roscore_daemon/start

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