

# Running Gazebo Simulator

Next build everything by running `catkin_make`. Then run the following command:

```
roslaunch robosub_simulator gazebo.launch
```

this will load the proper param files, start up gazebo with the correct world, spawn the sub, and finally, start the simulator bridge. At this point the control system, hydrophones, vision, etc are all ready to run.

From:

<https://robosub.eecs.wsu.edu/wiki/> - **Palouse RoboSub Technical Documentation**

Permanent link:

<https://robosub.eecs.wsu.edu/wiki/cs/simulator/run/start?rev=1481921103>



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