

# Simulator

## Gazebo Install

The current simulator uses Gazebo and is integrated with ROS. To install gazebo follow [these directions](#). For information about running the simulator [look here](#).

From:

<https://robosub.eecs.wsu.edu/wiki/> - **Palouse RoboSub Technical Documentation**

Permanent link:

<https://robosub.eecs.wsu.edu/wiki/cs/simulator/start?rev=1481585376>



Last update: **2016/12/12 15:29**