Legacy Image Tagging

Sloth

Setup

In order to tag images, we use a piece of software called Sloth. To install it from the robosub debian repository, run the following command:

```
sudo aptitude install sloth
```

Now that you have sloth, you need to clone the `vision_dev` repository. To do that, run this command wherever you want to clone it:

**Using an SSH key** (Do this if you have completed the Getting Started setup):

```
git clone git@github.com:PalouseRobosub/vision_dev.git
```

**Without an SSH key:**

```
git clone https://github.com/PalouseRobosub/vision_dev.git
```

Using Sloth

To use sloth and start tagging images, you can run the following command.

```
sloth -c /path/to/vision_dev/sloth/robosub_config.py /path/to/annotation/file
```

*-c* is a flag to give the path to a configuration file. This file is provided in the `vision_dev/sloth` directory. The path you provide should point to this file.

The last argument is a path to an annotation file. This is most likely named something like `labels.json`. You will need to provide this path in order to tag images.

Should you find this tedious, there is a script in the sloth directory of the `vision_dev` repository which performs some of this for you. It can be used as follows:

```
./robosub_sloth.sh /path/to/annotation/file
```

This removes the need to add the -c flag repeatedly. This script can also be symlinked to without issues.
Sloth alias

You can set up an alias in your bashrc. To do so run (replace "~/vision_dev" with path to your vision_dev repo):

```
export sloth='~/vision_dev/sloth/./robosub_sloth.sh'
```

```
s arrests sloth >> ~/.bashrc
source ~/.bashrc
```

Sloth Keybindings

The full list of keybindings used in sloth can be found in the robosub_config.py file near the bottom. A shorthand list is provided below.

**Default keybindings**

- **Space**: Mark image as labeled/confirmed and go to next
- **Backspace**: Next image/frame
- **PgDown**: Previous image/frame
- **PgUp**: Previous image/frame
- **Tab**: Select next annotation
- **Shift+Tab**: Select previous annotation
- **Ctrl+f**: Fit current image/frame into window
- **Del**: Delete selected annotations
- **Esc**: Exit insert mode
- **Shift+l**: Mark image as labeled
- **Shift+c**: Mark all annotations in image as confirmed

**Robosub Specific**

- **F5**: Toggle the visibility of label names on annotation boxes
- **Ctrl+Shift+D**: Delete all annotations from the current image and mark it as unlabeled
- **c**: Copy all annotations from the previous image to this one
- **n**: Mark image as labeled/confirmed and copy annotations to next image.
  (Equivalent to **Space** then **c**)

**Annotations**

- **s**: Start Gate Post
- **p**: Path Marker
- **t**: Torpedo Target
- **w**: Roulette Wheel
- **1**: Die 1
- **2**: Die 2
- **3**: Die 3
Sloth Mouse Controls

While creating annotations, the following are useful mouse controls.

- **Right Click and Drag**

  Resize an annotation. Resizing is based upon the quadrant of the annotation clicked on.

- **Ctrl+Left Click**

  Select multiple annotations at once.

Data Management

For Linux Users

Getting, validating, and returning labeling data is handled through the `rslabel` utility program. It currently only supports python 2.x versions. To install it, run

```
sudo pip install rslabel
```

To update `rslabel` for new features run

```
sudo pip install --upgrade rslabel
```

There are a number of commands to be used with `rslabel`, including show, get, return, upload, and collect.

<table>
<thead>
<tr>
<th>Command</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>rslabel show</code></td>
<td>Provides information about the number of datasets labeled, number of images properly validated, and counts any labeling sessions in progress.</td>
</tr>
<tr>
<td><code>rslabel get</code></td>
<td>Grabs an image dataset for labeling and places it in your current directory. The <code>-v</code> flag can be supplied to get labeled data to validate. The <code>--clarification</code> flag can be supplied to get labeled data to clarify. However, validation and clarification are done only by few assigned people in charge of object detection.</td>
</tr>
<tr>
<td><code>rslabel return [JSON]</code></td>
<td>Returns a dataset to the server. If the data has not been completely labeled or validated, it will be returned for someone else to complete in the future.</td>
</tr>
<tr>
<td>Command</td>
<td>Description</td>
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<tr>
<td>rslabel upload [ROSBAG]</td>
<td>Takes a ROS bag file and break the images out into datasets for labeling. It will then upload the files to the server for labeling.</td>
</tr>
<tr>
<td>rslabel collect</td>
<td>Collects all of the labeled and validated images into a single dataset for use with object detection training.</td>
</tr>
<tr>
<td>rslabel mark</td>
<td>A tool which is used for validating data, highlights the box which is there.</td>
</tr>
<tr>
<td>rslabel stats</td>
<td>This command will show scoreboard table: how many images labeled, how many labels added, how many images validated and how many labels validated.</td>
</tr>
</tbody>
</table>

**For Windows Users**

People who want to label on Windows you can use this tool to check, download and upload labels. To use this just extract the folder in zip anywhere and run `WindowsSftp.exe`, remember that `.dll` file must be in the same folder as `.exe`

```
robosub-windows-tools.zip
```

From: [https://robosub.eecs.wsu.edu/wiki/](https://robosub.eecs.wsu.edu/wiki/) - Palouse RoboSub Technical Documentation

Permanent link: [https://robosub.eecs.wsu.edu/wiki/cs/vision/image_tagging/legacy_tagging](https://robosub.eecs.wsu.edu/wiki/cs/vision/image_tagging/legacy_tagging)

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